Parameter Estimation for Single Diode Models of Photovoltaic Modules

Clifford W. Hansen

Prepared by
Sandia National Laboratories
Albuquerque, New Mexico 87185 and Livermore, California 94550

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Clifford W. Hansen
Photovoltaic and Distributed Systems Integration Department
Sandia National Laboratories
P.O. Box 5800
Albuquerque, New Mexico 87185-1033

Abstract

Many popular models for photovoltaic system performance employ a single diode model to compute the I-V curve for a module or string of modules at given irradiance and temperature conditions. A single diode model requires a number of parameters to be estimated from measured I-V curves. Many available parameter estimation methods use only short circuit, open circuit and maximum power points for a single I-V curve at standard test conditions together with temperature coefficients determined separately for individual cells. In contrast, module testing frequently records I-V curves over a wide range of irradiance and temperature conditions which, when available, should also be used to parameterize the performance model.

We present a parameter estimation method that makes use of a full range of available I-V curves. We verify the accuracy of the method by recovering known parameter values from simulated I-V curves. We validate the method by estimating model parameters for a module using outdoor test data and predicting the outdoor performance of the module.
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NOMENCLATURE

DOE  Department of Energy
SAPM  Sandia Array Performance Model
SNL  Sandia National Laboratories
STC  standard test conditions
1. INTRODUCTION

Many popular models for photovoltaic system performance (e.g., [1], [2]) employ a single diode model (e.g., [3]) to compute the I-V curve for a module or string of modules at given irradiance and temperature conditions. A single diode model requires a number of parameters to be estimated from measured I-V curves. Many available parameter estimation methods use only short circuit, open circuit and maximum power points for a single I-V curve at standard test conditions together with temperature coefficients determined separately for individual cells. In contrast, module testing frequently records I-V curves over a wide range of irradiance and temperature conditions, such as those specified in IEC 61853-1, which, when available, should also be used to parameterize the performance model.

Parameter estimation for single diode models has been challenging due to the model’s use of an implicit equation describing the relationship between current and voltage. Many available estimation methods rely on simplifying approximations, with attendant error, or optimization methods (e.g., [4]) that may be challenged to obtain reliable parameter values. Many methods (e.g., [5]) also use only a single I-V curve measured at standard test conditions (STC) whereas module testing can produce a wealth of I-V curves measured for a wide range of conditions.

We present an estimation method that avoids several commonly-used simplifying approximations and makes use of a full range of I-V curves. Our method was motivated by the approach outlined by Ortiz-Conde et al. [6].

In Section 2, we present a single diode model [2] which we use to illustrate our parameter estimation method. Because the heart of our technique is an algorithm to extract values for individual I-V curves, our method can be readily adapted to other single diode models (e.g., [1]). We review many of the available parameter estimation methods in Section 3, and present our method in Section 4. In Section 5 we verify that our method reproduces parameters for simulated I-V curves, demonstrate that it is robust in the presence of measurement error, and present validation of the model resulting from our parameter estimation method for a representative mono-crystalline silicon module.

2. SINGLE DIODE MODELS

A model for the electrical characteristic of a solar cell (e.g., [2], Eq. 1) can be derived from physical principles (e.g., [3]) and is often formulated as an equivalent circuit comprising a current source, a diode, a parallel resistor and a series resistor (Figure 1). For a module comprising \( N_s \) identical cells in series, use of the Shockley diode equation and summation of the indicated currents results in the single diode equation for the module’s I-V characteristic ([3], Eq. 3.154):

\[
I = I_L - I_O \left[ \exp \left( \frac{V + IR_s}{nV_{th}} \right) - 1 \right] - \frac{V + IR_s}{R_{shi}}
\]

where

- \( I_L \) is the photo-generated current (A),
- \( I_O \) is the dark saturation current (A),
- \( n \) is the diode ideality factor (unitless),
- \( V_{th} = N_s kT_c/q \) is termed the thermal voltage (V) for the module, which is determined from cell temperature \( T_c \) (K), Boltzmann’s constant \( k \) (J/K) and the elementary charge \( q \) (coulomb),
- \( k \) is Boltzmann’s constant \((1.38066 \times 10^{-23} \text{ J/K})\),
- \( q \) is the elementary charge \((1.60218 \times 10^{-19} \text{ coulomb})\),
- \( R_s \) is the series resistance (\( \Omega \)),
- \( R_{shi} \) is the shunt resistance (\( \Omega \)).

In this report, values for \( R_s \) and \( R_{shi} \) are considered at the module level; average values for the cells comprising a module can be obtained from the module values (e.g., [7]). Figure 2 displays an example I-V characteristic.

![Single diode equivalent circuit for a PV cell or module.](image-url)
Eq. (1) describes the single I-V curve given by the values of the parameters $I_L$, $I_O$, $R_S$, $R_{SH}$, and $n$ at as-yet unstated irradiance and temperature conditions. The effects of these conditions on the I-V curve are described by additional equations that define how each of the five parameters change with cell temperature $T_c$ and effective irradiance $E$, i.e., the irradiance that is converted to electrical current which differs from broadband plane-of-array (POA) irradiance (typically measured with a pyranometer) due to reflection losses, solar spectrum mismatch and other factors. Together Eq. (1) and these auxiliary equations comprise a complete model for the electrical performance of a module over all irradiance and temperature conditions.

Here, our focus is on methods to estimate all parameters for single diode models comprising Eq. (1) together with a suitable collection of auxiliary equations. We demonstrate our techniques using the single diode model described by De Soto et al. [2] which supplements Eq. (1) with the following auxiliary equations:

$$I_L = I_{L0} (E, T_c) = \frac{E}{E_0} [I_{L0} + \alpha_{bc} (T_c - T_0)]$$

$$I_O = I_{O0} (T_c) = I_{O0} \left[ \frac{T_c}{T_0} \right]^3 \exp \left[ \frac{1}{k} \left( \frac{E_g (T_0)}{T_0} - \frac{E_g (T_c)}{T_c} \right) \right]$$

$$E_g (T_c) = E_g (1 - 0.0002677 (T_c - T_0))$$
\[ R_{SH} = R_{SH0} \frac{E_0}{E} \]  \hspace{1cm} (5)

\[ R_S = R_{S0} \]  \hspace{1cm} (6)

\[ n = n_0 \]  \hspace{1cm} (7)

In Eq. (2) through Eq.(7), the subscript \( \sim_0 \) indicates a value at the reference conditions \( E_0 \) and \( T_0 \) for irradiance and cell temperature, respectively; typical values are \( E_0 = 1000 \text{ W/m}^2 \) and \( T_0 = 298 \text{K} \). Other choices are available for the auxiliary equations, the use of which results in different single diode models (e.g., [1]).

In this paper we refer to Eq. (1) as the single diode equation and to Eq. (1) together with auxiliary equations as the single diode model. The term “five parameter model” is often used to refer to a single diode model that incorporates Eq. (1); this term arises from the presence of the coefficients \( I_L, I_O, R_S, R_{SH}, \) and \( n \) which are commonly referred as the “five parameters.” The term “five parameter model” is imprecise when used to refer to a complete model comprising Eq. (1) along with the auxiliary equations, because the auxiliary equations contain the model’s parameters whereas the single diode equation itself does not. For the exemplary single diode model considered here, the parameters are \( n_0, I_{O0}, I_{Lo}, R_{SH0}, R_{S0} \) and \( E_{g0} \), \( \alpha_{inc} \); it is these values which must be determined from measurements, i.e., from a set of I-V curves measured at various levels of irradiance and cell temperature.
3. REVIEW OF AVAILABLE PARAMETER ESTIMATION METHODS

A successful parameter estimation method should satisfy the following criteria:

1) robust – the method should obtain parameter values for a wide range of module technologies and in the presence of reasonable measurement errors.
2) reliable – the method should obtain the same parameter values repeatedly when applied to the same data by different analysts.
3) accessible – the method should be fully documented and readily implemented and used by anyone with an adequate general background in PV modeling and in numerical analysis techniques.

We use these criteria to guide our review of existing methods, although we do not attempt to assign quantitative ratings to different methods according to these criteria.

The literature describing proposed methods for extracting values for the five parameters appearing in Eq. (1) is extensive; as early as 1986, proposed methods were sufficiently numerous to merit comparative studies (e.g., [8]). A recent survey of published methods is found in [6]. Here, we do not attempt a comprehensive literature survey; instead we cite examples that illustrate different approaches to parameter estimation and comment on the obstacles to meeting the criteria of reliability, precision and robustness. We emphasize that all published methods we reviewed were successful in extracting parameters for which the computed I-V curves reasonably matched the data. We considered these numerically successful methods in light of our criteria — robustness; reliability; and accessibility — to identify methods which could be candidates for a widely-adopted standard.

Some proposed methods (e.g., [9]; [10]) simplify or replace the diode equation Eq. (1) to overcome its implicit nature before extracting parameters. We did not pursue these techniques, because fundamentally, they estimate parameter values for a model different than that described by Eq. (1).

Techniques that do not simplify the diode equation can be divided roughly into two categories: methods that use only a manufacturer’s data sheet, (e.g., [11]); and methods that use, in some manner, a range of I-V curves. Here, we do not investigate approaches that use only data sheet information although that problem is of significant practical interest; our focus is on obtaining model parameters from a set of measured I-V curves.

Most methods find values for parameters by solving a system of non-linear equations. Typically, a system of non-linear equations is formulated by evaluating Eq. (1) at specific conditions to obtain equations corresponding to different points on the I-V curve and minimizing the difference between these points and the corresponding measured values. For example, [2], [7] and [5] evaluate Eq. 1 at standard test conditions (STC) for the short-circuit, open-circuit and maximum power points and subtract the measured values to obtain three equations involving five unknowns; a fourth equation is obtained by setting \( \frac{dP}{dV} = 0 \) at the maximum power point, and a fifth equation is obtained by translating an I-V curve to a cell temperature different from STC (using temperature coefficients determined by some other method). Other proposed methods obtain a system of equations by making approximations to Eq. (1) over parts of its domain (e.g., [12], [13]) or to equations derived from Eq. (1) (e.g., [14], [15], [16]). The system of equations is then solved by a numerical technique: proposed methods include root-finding (e.g., [4], [7]) and global optimization (e.g., [17], [18]). We note that these methods require nested numeric evaluations: (i) to solve Eq. (1) for current (or voltage) (e.g., [4]) for particular values for parameters, and (ii) to adjust parameter values to minimize the error metric.
Root-finding and optimization methods require initial estimates of parameter values, selection of an error metric, and setting of conditions to determine convergence. Different choices for these aspects may result in different parameter values being obtained from the same data set. From the point of view of our desired criteria, the primary weakness of parameter estimation methods using root-finding and optimization techniques is achieving reliability because it is common for these methods to fail to converge unless initial estimates of parameters are sufficiently close to optimum. Reliability may be achieved by proscribing initial conditions, error metrics and convergence tolerances, if practical, although evidence suggests that proscribed initial conditions may in turn compromise robustness (e.g., [4]).

A challenge common to all parameter estimation methods arises from the widely disparate magnitudes of terms appearing in Eq. (1). For $V$ near $V_{OC}$, for a 72-cell module the argument $(V+IR_S)/N_S nV_{th}$ of the exponential term in Eq. (1) takes values on the order of 30 (i.e., $30 \approx (50+IR_S)/72 \times 1.1 \times 0.02$). Unless $R_{SH}$ is unreasonably small (i.e., on the order of $5\Omega$) so that the term $(V+IR_S)/R_{SH}$ becomes comparable to the photocurrent $I_L \approx 8$A, $I_L$ must be offset by $I_o \left[ \exp\left( (V+IR_S)/N_S nV_{th} \right) - 1 \right]$ in order for current $I$ to be near 0. Consequently in this region of the I-V curve $I_o \approx \exp(-30) \approx 10^{-13}$, and relatively small changes in the estimated value for the diode factor $n$ (e.g., from 1.1 to 1.15) cause large changes to the value for $I_o$ (e.g., by a factor of more than 3). Multivariable optimization techniques, particularly root-finding methods that rely on derivatives (e.g., Newton’s method) or on domain partitioning (e.g., the Nelder-Mead method) may be challenged to overcome these greatly different scales and update individual parameter values appropriately.

Many methods simplify the system of equations by estimating certain parameters directly from the data by means of approximations. Commonly, e.g., [15], [19], $R_{SH}$ is approximated as

$$R_{SH} \approx \left. \frac{dV}{dI} \right|_{I=I_{SC}}$$

from which a value for $R_{SH}$ is obtained by some kind of numerical differentiation or curve fitting. The value for $R_{SH}$ is then imposed when estimating the remaining parameters. While these methods appeal due to the reduction in dimension of the optimization problem, the resulting parameter values are likely to be biased, or result in inconsistencies among the parameter values for an I-V curve (i.e., Eq. (1) becomes an inequality) due to biases inherent in the approximation. For example, if Eq. (8) is used, the values for $R_S$ are likely to be unreasonably small; see Appendix E for details.

Other methods (e.g., [12], [14], [20]) simplify the resulting system of equation by dividing $[0, V_{OC}]$ into several intervals and formulating different systems of equations for each interval. Within a given interval the system of equations may be simplified by approximations and certain parameters are estimated from data in regions where those parameters are most influential. These methods are often attractive because they can be motivated by the behavior of the physical system being modeled. However, they are also difficult to formulate to meet the reliability criterion. The boundaries between the intervals comprising $[0, V_{OC}]$ must be defined, which often is done by visual examination of data rather than algorithmically, and different choices of
boundaries will result in different subsets of data being used to estimate each parameter with consequent differences in parameter values.

Among the surveyed literature we found several approaches ([6], [21], [22]) that consider the full range of each I-V curve and make no simplifying approximations. For example, [6] and [21] fit the integrated single diode equation to corresponding integrated data by regression instead of estimating coefficients by fitting the single diode equation (Eq. (1)) to data directly; these methods differ in the variable of integration (voltage in the case of [6]; current in the case of [21]). Fitting to integrated data may offer the advantage of suppressing the effects of random measurement error. Our proposed method (Section 4.2) was initially motivated by [6]. However, upon implementation and testing of [6], we found problems stemming from the use of regression. Colinearity of the predictors in the regression and inaccuracy in the numerical integration procedure compromised the method’s reliability resulting in parameter values which were unduly sensitive to small changes in the data. We attempted to overcome these problems by adding elements of our own innovation.

Finally, [22] fits the derivative $dI/dV$ determined from the single diode equation to values estimated by numerical differentiation of measured I-V curves. Error in the measurements of current and/or voltage may be amplified by direct numerical differentiation; consequently, the method in [22] smooths the data by fitting polynomials before differentiation, a step which may not be necessary for methods using integrated quantities.
4. NEW PARAMETER ESTIMATION METHOD

Here we present an algorithm for estimating the parameters for the single diode model outlined in Section 2. The core of the algorithm is a technique for fitting the single diode equation (Eq. (1)) to each of a set of measured I-V characteristics, thus obtaining, for each I-V curve, a set of five coefficient values (i.e., \( I_L, I_O, R_s, R_{SH}, \) and \( n \)). Parameter values for the single diode model are then obtained by regressing the coefficients onto the irradiance and temperature conditions at which each I-V curve was measured.

The algorithm is demonstrated for the single diode model described in [2] but, with suitable modification, can be applied to any single diode model incorporating Eq. (1).

We first describe techniques for solving Eq. (1) analytically and numerically (Sect. 4.1) followed by an outline of our parameter estimation algorithm (Sect. 4.2).

4.1. Analytic and Numerical Solutions for Single Diode Equation

Eq. (1) cannot be solved for current (or voltage) explicitly using elementary functions. However, current can be expressed as a function of voltage \( I = I(V) \) (or \( V = V(I) \)) by using the transcendental Lambert’s W function [23] as presented by several authors ([24], [25]). Lambert’s W function is the solution \( W(x) \) of the equation \( x = W(x) e^{W(x)} \). Using this function we may write \( I = I(V) \):

\[
I = \frac{R_{SH}}{R_{SH} + R_s} (I_L + I_O) - \frac{V}{R_{SH} + R_s} - \frac{nV_{th}}{R_s} W\left(\frac{R_s I_O}{R_{SH} + R_s} \exp\left(\frac{R_{SH}}{R_{SH} + R_s} \frac{R_s (I_L + I_O) + V}{nV_{th}}\right)\right)
\]

(9)

or \( V = V(I) \); see Appendix A for the derivations.

\[
V = (I_L + I_O - I) R_{SH} - nV_{th} W\left(\frac{I_O R_{SH}}{nV_{th}} \exp\left(\frac{(I_L + I_O - I) R_{SH}}{nV_{th}}\right)\right)
\]

(10)

For convenience we introduce two variables

\[
\theta = \frac{R_s I_O}{nV_{th}} \frac{R_{SH}}{R_{SH} + R_s} \exp\left(\frac{R_{SH}}{R_{SH} + R_s} \frac{R_s (I_L + I_O) + V}{nV_{th}}\right)
\]

(11)

and

\[
\psi = \frac{I_O R_{SH}}{nV_{th}} \exp\left(\frac{(I_L + I_O - I) R_{SH}}{nV_{th}}\right)
\]

(12)

which permit Eq. (9) and Eq. (10) to be written compactly as

\[
I = \frac{R_{SH}}{R_{SH} + R_s} (I_L + I_O) - \frac{V}{R_{SH} + R_s} - \frac{nV_{th}}{R_s} W\left(\theta\right)
\]

(13)

and
respectively.

Lambert’s W function can be efficiently evaluated with very high precision [26]; thus Eq. (9) and Eq. (10) can be directly implemented for most of the range of an I-V curve. However, for Eq. (10) approaching \( V_{oc} \) (i.e., as current \( I \) becomes small), numerical overflow becomes a problem. For example, for \( I_o = 10^{-9} \) A, \( R_{sh} = 1000 \Omega \), \( n = 1.05 \), \( I_L = 6 \) A (typical for a 72 cell module), and \( V_{th} = 1.973 \), the argument \( \psi \) of the \( W \) function in Eq. (10) exceeds numerical overflow for 64-bit machines (approximately \( 10^{308} \)) for \( I < 4.5 \) A. To compute this portion of the I-V curve we use logarithms as described in Appendix B.

4.2. Method Description

We propose a sequential approach to obtaining single diode model parameters from measured I-V curves. Throughout the process, we solve Eq. (1) using Lambert’s W function (e.g., by Eq. (9) and Eq. (10)). Using Lambert’s W function confers several advantages:

- Numerical computation is quite fast, requiring very little iteration. By contrast, other parameter estimation methods (e.g., [4]) solve Eq. (1) using fixed-point methods, which may require significantly more computational effort;
- Derivatives (e.g., \( dI/dV \)) can also be expressed exactly using the W function avoiding the pitfalls of estimating derivatives numerically;
- Asymptotic approximations for W are relatively simple which allows certain parameter estimation steps to be confirmed analytically.

Figure 3 illustrates our parameter estimation method. We illustrate the steps of our method using data measured on a two-axis tracker for a 96-cell (i.e., \( N_S = 96 \)), mono-crystalline cSi module.

**Step 1: Temperature coefficients.**

We first determine temperature coefficients \( \alpha_{isc} \) and \( \beta_{voc} \) for short-circuit current \( I_{sc} \) and open-circuit voltage \( V_{oc} \), respectively, from I-V curves with irradiance near STC (i.e., 1000 W/m²). We employ linear regression as specified in IEC 60891 [27] and as has been extensively and successfully used ([28], [29]) for the Sandia Array Performance Model (SAPM) [30]. Only \( \alpha_{isc} \) appears explicitly in the performance model outlined in Sect. II, although to apply Step 2 of our method to the exemplary single diode model [2] we also need \( \beta_{voc} \).
For determination of temperature coefficients from measurements, we assume that I-V curves are measured outdoors with air mass near 1.5 and angle of incidence zero, or indoors using a flash tester calibrated to these conditions. Irradiance should be maintained near 1000 W/m² while module temperature is varied; generally a range of 25°C is sufficient. For determination of temperature coefficients effective irradiance $E$ is preferably measured using a matched reference cell, but it is acceptable to use broadband POA irradiance $G_{POA}$ measured with a pyranometer instead.

Open-circuit voltage $V_{OC}$ is empirically related to cell temperature $T_C$ and effective irradiance $E$ by ([30], Eq 3 and Eq 7):

$$V_{OC} = V_{OC0} + nV_{th} \ln \left( \frac{E}{E_0} \right) + \beta_{V_{OC}} (T_C - T_0)$$  \hspace{1cm} (15)

where
- $T_0$ is the reference temperature assumed for these parameters (typically 25°C),
- $E_0$ is the reference irradiance assumed for these parameters (typically 1000 /m²), and
- $V_{OC0}$ is $V_{OC}$ at the reference conditions.
Appendix D demonstrates that the empirical relationship between $V_{OC}$ and $E$ in Eq. (15) is asymptotically consistent with the single diode model described in Sect. 2. The linear relationship between $V_{OC}$ and $T_C$ is outlined for the single diode model in [3], Eq. 3.165.

We assume a value for $n$ typical for the module’s cell type (i.e., $n = 1.1$ for cSi cells, $n = 1.3$ for thin-film single junction cells), and rearrange Eq. (15) to

$$V_{OC} - nV_{th} \ln\left(\frac{E}{E_0}\right) = V_{OC0} + \beta_{Voc} \left(T_C - T_0\right)$$

(16)

Regression obtains $\beta_{Voc}$ as illustrated by Figure 4.

\[
Y = 64.26 + -0.1874X \\
\beta_{Voc} = -0.1874
\]

\[T_C - 25 \text{ (°C)}\]

**Figure 4. Example of determination of $\beta_{Voc}$**

Because I-V curves are measured with $E$ close to 1000 W/m² the term $nV_{th} \ln\left(\frac{E}{E_0}\right)$ should be small compared to measured $V_{OC}$. Consequently any inaccuracy in $nV_{th} \ln\left(\frac{E}{E_0}\right)$ resulting from the assumed value for $n$ will have little effect on the value for $\beta_{Voc}$.

We express the change in $I_{SC}$ with temperature as

$$I_{SC} = I_{SC0} \frac{E}{E_0} \left[1 + \alpha_{Isc} \left(T_C - T_0\right)\right]$$

(17)

where $I_{SC0}$ and $\alpha_{Isc}$ are unknown terms. We re-arrange to obtain
\[ I_{sc} \frac{E}{E} = I_{sc} \left( 1 + \alpha_{isc} \left( T_c - T_0 \right) \right) \]
\[ = \beta_0 + \beta_1 \left( T_c - T_0 \right) \]

Using measured \( I_{sc} \), \( E \) and \( T_c \), a linear, least-squares regression obtains coefficients \( \beta_0 \) and \( \beta_1 \), from which \( \alpha_{isc} \) is determined:

\[ \alpha_{isc} = \frac{\beta_1}{\beta_0} \].

Figure 5 illustrates the determination of \( \alpha_{isc} \).

\[ Y = 5.89 + 0.00187X \]
\[ a_{isc} = 0.00187/5.8929 = 0.000317 \]

**Step 2: Diode factor.**

In the exemplary single diode model [2], \( n \) is considered to have the same, constant value for all conditions. We estimate \( n \) from the relationship between \( V_{oc} \) and effective irradiance \( E \). From Eq. (10) we obtain

\[ V_{oc} = (I_e + I_0)R_{Sth} - nV_{th} \left( \frac{I_o R_{Sth}}{nV_{th}} \exp \left( \frac{(I_e + I_0)R_{Sth}}{nV_{th}} \right) \right) \]
Asymptotic analysis (Appendix D) shows that when $T_c = T_0$, to first order

$$V_{OC} - V_{OC0} \approx nV_{th} \ln\left(\frac{E}{E_0}\right)$$  \hspace{1cm} (21)

which is the same expression as is used in [30] (i.e., Eq. (15) in this presentation). Accordingly, we use Eq. (15) to obtain $n$ from a linear regression:

$$V_{OC} - \beta_{Voc} (T_c - T_0) = V_{OC0} + nV_{th} \ln\left(\frac{E}{E_0}\right)$$  \hspace{1cm} (22)

Figure 6 illustrates the determination of $n$. For the regression in Figure 6, I-V curves are required over a range of irradiance, preferably from 400 W/m² to 1000 W/m².

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{figure6.png}
\caption{Example of determination of $n$.}
\end{figure}

**Step 3. Values for $R_{SH}$, $R_S$, $I_O$ and $I_L$ for each I-V curve.**

These parameters are estimated using an iterative procedure: initial estimates are obtained, and then the estimates are updated sequentially until convergence criteria are satisfied.

**Step 3a: Initial estimates.** For each I-V curve, we determine an initial value for $R_{SH}$, $R_S$, $I_O$ and $I_L$. We obtain the initial estimate for $R_{SH}$ with a regression involving the co-content $CC$, i.e., an integral of the I-V curve over voltage, which method is an improvement upon that
presented in [6]. We then use the value for $R_{SH}$ to obtain initial estimates for $I_D$, $R_S$, and $I_L$ in that order.

In [6], the co-content is stated to be exactly equal to a polynomial in $V$ and $I = I(V)$ (details are shown in Appendix C):

$$CC(V) = \int_0^V (I_{SC} - I(v)) dv = c_1 V + c_2 (I_{SC} - I) + c_3 V (I_{SC} - I) + c_4 V^2 + c_5 (I_{SC} - I)^2$$  \hspace{0.5cm} (23)

As presented in [6], the integral in Eq. (23) is evaluated numerically by a trapezoid rule, the coefficients $c_i$ are determined by multiple linear regression, and values for all five parameters $I_L$, $I_D$, $R_S$, $R_{SH}$, and $n$ are then determined from the coefficients $c_i$. For example

$$R_{SH} = 1/2c_4 \hspace{0.5cm} ([6], \text{Eq. 11})$$  \hspace{0.5cm} (24)

and

$$R_S = \sqrt{1+16c_4c_5} - 1 \hspace{0.5cm} (4c_4) \hspace{0.5cm} ([6], \text{Eq. 12})$$  \hspace{0.5cm} (25)

When applied to various sets of I-V curves, we found this approach to be occasionally problematic for $R_{SH}$ and sometimes unreliable for the other parameter values. For example, we occasionally obtained negative values for $R_{SH}$ for I-V curve data without obvious flaws such as upward trending current, and also obtained negative or imaginary values for $R_S$ [31]. Investigation revealed two related causes for failure of this method:

- Colinearity between predictors in Eq. (23),
- Numerical error in computing the integral for $CC$.

Due to the colinearity between predictors over much of the I-V curve, small variations in predictors due to measurement error, and variations in the predictand due to numerical error, resulted in unreliable parameter estimates. For example, we found that simple trapezoid integration led to frequent failure to obtain reasonable parameter values, and to systematic biases in the parameter values that were found. These obstacles may be overcome to some extent by computing the integral using a spline (i.e., a quadratic spline that respects the decreasing, convex shape of the I-V curve) and performing a transformation before the regression that makes several predictors orthogonal. Appendix C provides details behind the spline approximation and the principal components transformation.

With these improvements we obtain reasonable values for $R_{SH}$ for nearly all I-V curves. We then use the condition $R_{SH} > 0$ as a quality filter to remove I-V curves with upward-trending current from further consideration (e.g., Figure 7).
Figure 7. Examples of measured I-V curves for which $R_{SH} < 0$.

Even when a reasonable value for $R_{SH}$ is obtained, values for $I_O$, $R_s$ and $I_L$ from the method in [6] sometimes can result in negative or imaginary values due to their dependence on several of the regression coefficients; for example, in the method in [6] $R_s$ depends on two coefficients (Eq. (25)). Our improvements upon [6] obtain reasonable values for $I_O$, $R_s$, and $I_L$ more often, but not always. Consequently we disregard the values for $I_O$, $R_s$, and $I_L$ resulting from the regression method and instead estimate values for $I_O$, $R_s$, and $I_L$ in that order, in a different manner.

We first note that at open circuit, $I = 0$ and the single diode equation has no dependence on $R_s$:

$$0 = I_L - I_O \left[ \exp \left( \frac{V_{OC}}{nV_{th}} \right) - 1 \right] - \frac{V_{OC}}{R_{SH}}$$

$$= (I_L + I_O) - I_O \left[ \exp \left( \frac{V_{OC}}{nV_{th}} \right) \right] - \frac{V_{OC}}{R_{SH}}$$

Approximating $I_L + I_O \approx I_{SC}$ in Eq. (26) obtains
0 \approx I_{SC} - I_O \left[ \exp \left( \frac{V_{OC}}{nV_{th}} \right) \right] - \frac{V_{OC}}{R_{SH}} 

The initial estimate of \( I_O \) is obtained from Eq. (27):

\[
I_O = \left( I_{SC} - \frac{V_{OC}}{R_{SH}} \right) \exp \left( -\frac{V_{OC}}{nV_{th}} \right)
\]

With a value for \( I_O \) in hand, the initial estimate of \( R_S \) is obtained from the slope of the I-V curve near \( V_{OC} \) (but not at \( V_{OC} \)). Ideally, the derivative \( \frac{dI}{dV} \) will be negative and smoothly decreasing as \( V \to V_{OC} \). Estimating the derivative from data requires use of some kind of numeric differentiation scheme. For measured I-V curves we cannot assume that the points comprising the I-V curve are taken at equally-spaced voltage values and consequently most common finite difference approximations (e.g., [32]) are not suitable. We employ a fifth order finite difference technique (i.e., Eq. A5b in [33]) which accommodates unequally-spaced data to estimate

\[
I'_V(V_k) = \left. \frac{dI}{dV} \right|_{V=V_k}, \quad k = 1, \ldots, M
\]

for data at voltages \( V_k \) where \( L = 0.5V_{OC} < V_k < 0.9V_{OC} = R \) and \( k = 1, \ldots, M \). Then, we estimate \( R_S \) as the average (Eq. (30))

\[
R_S \approx \frac{1}{M} \sum_{k=1}^{M} R_{S,k}
\]

where

\[
R_{S,k} = \frac{nV_{th}}{I_{SC}} \left[ \ln \left( -\left( R_{SH} I'_V(V_k) + 1 \right) \frac{nV_{th}}{R_{SH} I_O} \right) - \frac{V_k}{nV_{th}} \right]
\]

for points where \( R_{SH} I'_V(V_k) + 1 < 0 \).

Eq. (30) is derived from the exact expression for \( \frac{dI}{dV} \) as follows: Writing for simplification

\[
\theta = \theta(V) = \frac{R_S I_O}{nV_{th}} \frac{R_{SH}}{R_{SH} + R_S} \exp \left( \frac{R_{SH} R_S (I_L + I_O) + V}{R_{SH} + R_S} \frac{V}{nV_{th}} \right)
\]

and then differentiating Eq. (9) we obtain:

\[
\frac{dI}{dV} = -\frac{1}{R_{SH} + R_S} \left[ 1 + \frac{R_{SH}}{R_S} \frac{W(\theta)}{1+W(\theta)} \right]
\]

\[
= -\frac{1}{R_{SH} + R_S} \left[ 1 + \frac{R_{SH}}{R_S} \left( 1 - \frac{1}{1+W(\theta)} \right) \right]
\]
For most of the range of voltage of interest, we may assume that \( \theta \ll 1 \), consequently \( W(\theta) \approx \theta \) [23], and hence \( \frac{1}{1+W(\theta)} \approx \frac{1}{1+\theta} \approx 1-\theta \). Thus we obtain

\[
\frac{dI}{dV} \approx -\frac{1}{R_{SH} + R_s} \left[ 1 + \theta \frac{R_{SH}}{R_s} \right] \tag{34}
\]

Typically \( R_s \ll R_{SH} \) and we also assume \( I_L + I_O \approx I_{SC} \) so

\[
\theta \approx \frac{R_s I_O}{nV_{th}} \exp \left( \frac{R_s I_{SC} + V}{nV_{th}} \right) \tag{35}
\]

Combining Eq. (34) and Eq. (35)

\[
\frac{dI}{dV} \approx -\frac{1}{R_{SH}} \left[ 1 + \theta \frac{R_{SH}}{R_s} \right]
\]

\[-R_{SH} \frac{dI}{dV} \approx 1 + \frac{R_{SH} I_O}{nV_{th}} \exp \left( \frac{R_s I_{SC} + V}{nV_{th}} \right) \tag{36}
\]

which we solve for \( R_s \) to obtain Eq. (31).

When estimating an initial value for \( R_s \), care must be taken to exclude voltage points \( V_k \) where the term \( R_{SH} I'_V(V_k) + 1 > 0 \), which can occur for either a positive value for \( I'_V(V_k) \), indicative of questionable I-V curve data, or a negative but very small value for \( I'_V(V_k) \), which may occur for \( V \) substantially less than \( V_{MP} \). However, we found it necessary to include voltages less than \( V_{MP} \) in the average in Eq. (30) to obtain reasonable values for \( L \). We chose \( L = 0.5V_{OC} \) and \( R = 0.9V_{OC} \), where the right limit is set to exclude points where the numerical derivative \( I'_V(V_k) \) becomes inaccurate due to a lack of measurements or due to the assumption that \( \theta \ll 1 \) which may fail for \( V \) very near \( V_{OC} \).

Lastly, \( I_L \) is estimated by evaluating Eq. (1) at \( I_{SC} \):

\[
I_L = I_{SC} - I_O + I_O \exp \left( \frac{R_s I_{SC}}{nV_{th}} \right) + \frac{R_s I_{SC}}{R_{SH}} \tag{37}
\]

Step 3b: Filter out I-V curves with bad parameter sets. Once initial estimates are obtained, the algorithm filters the parameter sets to exclude I-V curves where the parameter estimates indicate problems. An I-V curve is excluded if the corresponding parameter estimates meet any of the following criteria:

- The value for \( R_{SH} \) is negative (indicating that current may be increasing with increasing voltage) or is indeterminate (indicating a lack of data or a problem with the regression which determines the coefficient \( c_4 \) in Eq. (24)).
The value for $R_s$ is negative, has a non-zero imaginary component, is indeterminate or is greater than $R_{sh}$.

The value for $I_O$ is zero, negative, or has a non-zero imaginary component.

In addition, the algorithm expects that the PV device is substantially linear, i.e., the measured short-circuit current $I_{sc}$ is nearly proportional to effective irradiance $E$ (or to broadband POA irradiance $G_{poa}$). An empirical efficiency $\eta$ is obtained by regressing $I_{sc}$ onto $E$, i.e.:

$$I_{sc} = \eta \frac{E}{E_0}$$

and the residual $\varepsilon = \eta \frac{(E/E_0) - I_{sc}}{I_{sc}}$ is used to exclude I-V curves where $|\varepsilon| > 0.05I_{sc}$ reasoning that these errors occur when there are substantial differences between $E$ (or $G_{poa}$) and $I_{sc}$ due to shading or other external factors. When these rules are applied to data obtained at SNL’s laboratory typically only a few (<1%) I-V curves are filtered out, and these I-V curves usually display obvious problems such as increasing current as voltage increases.

**Step 3c:** Update initial estimates of $R_{sh}$, $R_s$, $I_O$, and $I_L$ to obtain final values for each I-V curve. The initial estimates $R_{sh}$, $R_s$, $I_O$ and $I_L$ may result in poor matches to measured $V_{oc}$, $V_{mp}$ and $I_{mp}$. Parameters are updated in order as follows:

1. $R_{sh}$ is adjusted to match $V_{mp}$ by a fixed point iteration, using previous values for $R_s$, $I_O$ and $I_L$;
2. $R_s$ is updated to match $V_{mp}$ calculated using the new value for $R_{sh}$ and previous values for $I_O$ and $I_L$;
3. $I_O$ is adjusted to match $V_{oc}$ by a method similar to Newton’s method using new values for $R_{sh}$ and $R_s$ and the previous value for $I_L$;
4. $I_L$ is updated to match $I_{sc}$ by Eq. (37) using new values for $R_{sh}$, $R_s$ and $I_O$.

To adjust $R_{sh}$ we use Eq. (10) evaluated at the maximum power point:

$$V_{mp} = (I_L + I_O) R_{sh} - I_{mp} (R_{sh} + R_s) - nV_{th} W(\psi)$$

where

$$\psi = \frac{I_O R_{sh}}{nV_{th}} \exp \left( \frac{R_{sh} (I_L + I_O - I_{mp})}{nV_{th}} \right)$$

However, Eq. (40) holds for any point $(V, I)$ on the I-V curve. Consequently we use a second equation which defines the maximum power point:

$$0 = \frac{dP}{dI} \bigg| I = I_{mp} = (I_L + I_O - I_{mp}) R_{sh} - I_{mp} (R_{sh} + R_s) - nV_{th} W(\psi) + I_{mp} \left[ R_{sh} \frac{W(\psi)}{1 + W(\psi)} - (R_{sh} + R_s) \right]$$
Solving Eq. (39) and Eq. (41) for $R_s$ and equating the results to eliminate $R_s$ we obtain an expression involving $R_{sh}$, $I_O$, $I_L$ and the measured maximum power point $(V_{mp}, I_{mp})$:

$$0 = f(R_{sh} | I_O, I_L) = \frac{I_L + I_O}{2I_{MP}} - \frac{nV_{sh}W(\psi)}{2I_{MP}} - \frac{V_{MP} - W(\psi)R_{sh}}{1 + W(\psi)} \frac{R_{sh}}{2}$$

(42)

We solve for the updated value of $R_{sh}$ by fixing $I_O$ and $I_L$ at their previous values and applying fixed point iteration to the following re-arrangement of Eq. (42):

$$R_{sh,k+1} = \frac{1 + W(\psi)}{W(\psi)} \left[ \frac{I_L + I_O}{I_{MP}} R_{sh,k} - \frac{nV_{sh}W(\psi)}{I_{MP}} - \frac{2V_{MP}}{I_{MP}} \right]$$

(43)

Numerical tests with measured I-V curves for modules with a variety of cell technologies (including cSi and thin-film cells) indicate that Eq. (43) converges, although the rate of convergence is slow. Analytic proof that Eq. (43) is a contraction mapping appears formidable to accomplish; we see this part of the algorithm as an opportunity for research and improvement.

With an adjusted value for $R_{sh}$ the value for $R_s$ is updated to be consistent with the new value for $R_{sh}$ and the measured maximum power point using Eq. (39):

$$R_s = \frac{I_L + I_O}{I_{MP}} R_{sh} - \frac{nV_{sh}W(\psi)}{I_{MP}} - \frac{V_{MP}}{I_{MP}}$$

(44)

Next, $I_O$ is adjusted so that calculated $V_{oc}$ matches measured $V_{oc}$. Consider $V_{oc}(I_O)$ as a function of only $I_O$ (i.e., using Eq. (20) and fixing all parameters other than $I_O$ at their current values) and denote the measured $V_{oc}$ by $\hat{V}_{oc}$. We seek a value $\hat{I}_{oc}$ such that $V_{oc}(\hat{I}_{oc}) - \hat{V}_{oc} = 0$ and use a root-finding method akin to Newton’s method.

Differentiating Eq. (20) with respect to $I_O$ we obtain:

$$\frac{dV_{oc}}{dI_O} = R_{sh} - nV_{sh} \frac{W(\psi_{oc})}{1 + W(\psi_{oc})} \left[ \frac{1}{I_O} + \frac{R_{sh}}{nV_{sh}} \right]$$

(45)

where

$$\psi_{oc} = \frac{I_O R_{sh}}{nV_{sh}} \exp \left( \frac{(I_L + I_O) R_{sh}}{nV_{sh}} \right)$$

(46)

For most conceivable modules, we can safely assume that $\psi_{oc} >> 1$. The term $\exp \left( \frac{(I_L + I_O) R_{sh}}{nV_{sh}} \right)$ in Eq. (46) is orders of magnitude greater than the term $\frac{I_O R_{sh}}{nV_{sh}}$. For example, taking $I_O \sim 10^{-7} A$, a relatively large value, $I_L \sim 1A$ which is small for most modules, $nV_{sh} \sim 2$, and $R_{sh} \sim 100\Omega$, a relatively small value, leads to...
\[ \psi_{oc} \approx \frac{10^{-7} \times 100}{2} \exp\left(\frac{100}{2}\right) \approx 10^{-7} \exp(50) \sim 10^{14} \] (47)

Because we may assume that \( \psi_{oc} \gg 1 \), we may also assume that \( \frac{W(\psi_{oc})}{1 + W(\psi_{oc})} \approx 1 \) simplifying Eq. (45) to

\[ \frac{dV_{oc}}{dI_o} \approx \frac{-nV_{sh}}{I_o} \] (48)

Approximating \( V_{oc} \) as a linear function of \( I_o \) near \( \hat{I}_{oc} \):

\[ V_{oc}(I_o) \approx \hat{V}_{oc} + \frac{dV_{oc}}{dI_o} \bigg|_{I_o = \hat{I}_o} \times (I_o - \hat{I}_o) \] (49)

where the derivative is evaluated at \( I_o^* = \frac{I_o + \hat{I}_o}{2} \) also near \( \hat{I}_{oc} \). Because the curve described by \( (I_o, V_{oc}(I_o)) \) is concave upwards (per Eq. (48)) a better estimate of \( V_{oc}(I_o) \) is obtained from Eq. (49) by evaluating the derivative at the midpoint \( I^* = \frac{I_o + \hat{I}_o}{2} \) between \( I_o \) and \( \hat{I}_o \).

Combining Eq. (48) and Eq. (49)

\[ V_{oc}(I_o) \approx \hat{V}_{oc} + \frac{dV_{oc}}{dI_o} \bigg|_{I_o = \hat{I}_o} \times (I_o - \hat{I}_o) \]

\[ \approx \hat{V}_{oc} - \frac{2nV_{sh}}{I_o + \hat{I}_o} (I_o - \hat{I}_o) \] (50)

Solving for \( \hat{I}_o \) obtains

\[ \hat{I}_o \approx I_o \left[ \frac{\left( V_{oc}(I_o) - \hat{V}_{oc} \right) + 2nV_{sh}}{2nV_{sh} - \left( V_{oc}(I_o) - \hat{V}_{oc} \right)} \right] \]

\[ \approx I_o \left[ 1 + \frac{2 \left( V_{oc}(I_o) - \hat{V}_{oc} \right)}{2nV_{sh} - \left( V_{oc}(I_o) - \hat{V}_{oc} \right)} \right] \] (51)

As in Newton’s method we iterate Eq. (51) to obtain a sequence of values \( I_{o,k} \) converging to \( \hat{I}_o \):

\[ I_{o,k+1} = I_{o,k} \times \left[ 1 + \frac{2 \left( V_{oc}(I_{o,k}) - \hat{V}_{oc} \right)}{2nV_{sh} - \left( V_{oc}(I_{o,k}) - \hat{V}_{oc} \right)} \right] \] (52)

where we compute \( V_{oc}(I_{o,k}) \) using Eq. (20). Convergence of Eq. (52) is rapid; in our testing ten iterations suffice.
Lastly, $I_L$ is updated to match measured $I_{SC}$ using updated values for $R_{SH}$, $R_S$ and $I_o$ in Eq. (37).

**Step 3d: Test for convergence.** The parameter estimates for an I-V curve are considered converged when the maximum difference between the predicted $I_{MP}$, $V_{MP}$ and $P_{MP}$ and the corresponding measurements are all less than 0.002% of the measured values. We also fix an (arbitrary) upper limit on the number of iterations (e.g., 10). The threshold for precision and the iteration limit can be easily changed.

**Step 4. Parameter values for single diode model equations.**

Step 3 results in a set of parameter values corresponding to each measured I-V curve. In step 4 we relate the parameter values for each I-V curve to the irradiance and temperature conditions extant when the I-V curve was measured to determine the appropriate parameters for each auxiliary equation. The regressions involved necessarily depend on the particular single diode model being considered. Here we show how the model parameters appearing in the auxiliary equations of the single diode model in [2] (i.e., Eq. (2) through Eq. (7)) are determined. The parameters to be estimated are: $I_{L0}$, $I_{O0}$, $E_{g0}$, $R_{SH0}$, $R_{S0}$ and $n_0$. Throughout we recommend the use of a robust regression technique (e.g., iteratively reweighted least squares\(^1\)) to minimize the effects of outlier data, e.g., unfiltered I-V curves where the module and the irradiance sensor were exposed to somewhat different irradiance conditions.

**Light current at STC $I_{L0}$**. $I_{L0}$ is, by definition, the light current at STC conditions: POA irradiance of 1000 W/m\(^2\), cell temperature 25°C, and reference solar spectrum [34]. We estimate $I_{L0}$ from a subset of values of $I_L$ determined for each of the N I-V curves by filtering for irradiance conditions near STC. In our example here, we select I-V curves with POA irradiance within 100 W/m\(^2\) of 1000 W/m\(^2\). Absolute (i.e., pressure adjusted) air mass $AMa$ is often used as a surrogate for solar spectrum because it is easily calculated; we also filter for I-V curves within 0.5 units of $AMa=1.5$. We estimate $I_{L0}$ as the average of the values determined using Eq. (2) for each I-V curve in the selected subset indexed by $j=1,\ldots, M$:

$$I_{L0} = \frac{1}{M} \sum_{j=1}^{M} I_{L,j} \left[ \frac{E_0}{E_j} - \alpha_{bc} \left(T_{C,j} - T_0\right) \right]$$  \hspace{1cm} (53)

A value for $\alpha_{bc}$ should be determined from separate testing as described in Section 4.2, Step 1. Figure 8 illustrates the estimate of $I_{L0}$.

**Dark current $I_{O0}$ and band gap $E_{g0}$.** $I_{O0}$ and $E_{g0}$ are estimated jointly. Eq. (4) is substituted into Eq. (3) and the result is re-arranged to obtain:

$$\ln(I_O) - 3 \ln \left( \frac{T_C}{T_0} \right) = \ln(I_{O0}) + E_{g0} \left[ \frac{1}{k} \frac{1}{T_0} - \frac{1}{T_C} + 0.0002677 \frac{T_C - T_0}{T_C} \right]$$  \hspace{1cm} (54)

\(^1\) E.g., http://www.mathworks.com/help/stats/robustfit.html
Regression between $Y = \ln(I_o) - 3\ln \left( \frac{T_C}{T_0} \right)$ and 

$$X = \begin{bmatrix} 1 & \frac{1}{kT_0} & \frac{1}{T_C} & + 0.0002677 \frac{T_C - T_0}{T_C} \end{bmatrix},$$

i.e.,

$Y = X\beta$, obtains coefficients $\beta = \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix}$ from which

$$I_{o0} = \exp(\beta_1)$$

(55)

and

$$E_g0 = \beta_2$$

(56)

With suitable adjustment to $X$ the constant 0.0002677 can be replaced by an empirical value, although we have not observed any significant change in model prediction accuracy when this is done. Figure 9 illustrates the estimation of $I_{o0}$ and $E_{g0}$.
Figure 9. Determination of \( I_{00} \) and \( E_{g0} \).

In [2] and its implementation in the System Advisor Model (SAM)\(^2\), the parameter \( E_{g0} \) is specified to be the theoretical value for a silicon cell (1.12 eV) and this value is applied to most modules. We have found that empirical values are generally less than this theoretical value and that use of empirical values significantly improves the fitted model’s accuracy. Figure 10 compares model predictions using the empirical values and theoretical values for \( E_{g0} \).

Shunt resistance \( R_{SR0} \) and series resistance \( R_{S0} \). In [2] the parameters \( R_{SR0} \) and \( R_{S0} \) are intended to represent I-V curves at standard test conditions (STC). Accordingly we consider only I-V curves measured with effective irradiance exceeding 400 W/m\(^2\) to estimate values for \( R_{SR0} \) and \( R_{S0} \). The value for \( R_{SR0} \) results from a regression between \( Y = R_{SR} \) (i.e., the values determined for the set of I-V curves) and \( X = \frac{E_{0}}{E} \) to obtain \( Y = R_{SR0}X + \varepsilon \); no constant term is included in this regression model. The value for \( R_{S0} \) is set to equal the mean of the values for the considered I-V curves, i.e., \( R_{S0} = \frac{1}{K} \sum_{i=1}^{K} R_{S,i} \), where \( i = 1, \ldots, K \) enumerates I-V curves for which \( E > 400 \) W/m\(^2\). Figure 11 illustrates the estimation of \( R_{SR0} \) and \( R_{S0} \).

\(^2\) https://sam.nrel.gov/
As indicated in Figure 11 the specified models for $R_{sh}$ and $R_s$ may not always closely follow trends in the parameter values extracted from the measured I-V curves, especially at low irradiance. The differences between the model predictions and extracted values could result from deficiencies in the selected empirical models for the dependence of $R_{sh}$ and $R_s$ on irradiance and temperature, systematic biases in the extracted parameters, or from a more fundamental mismatch between the single diode equation and the I-V curve data. In any case, model prediction accuracy could be improved by adapting the expressions in Eq. (5) and Eq. (6) to more closely follow the trends in the extracted parameters.

Diode (ideality) factor $n_0$. We set $n_0 = n$ where $n$ is the constant determined in Eq. (22).
Figure 11. Determination of $R_{\text{SH}0}$ (top) and $R_{\text{S}0}$ (bottom).
5. VERIFICATION AND VALIDATION

We verify the accuracy of our method by computing simulated I-V curves and then applying our parameter estimation method to recover the parameters used to generate the simulated I-V curves. We validate our method by predicting outdoor performance of a representative module comprising mono-crystalline silicon cells. Parameters for a single diode model are estimated from a sample of I-V curves measured outdoors in Albuquerque, NM, and then module performance is predicted for measured, out-of-sample I-V curves.

5.1. Verification

5.1.1 Simulated modules for method verification

We used the single diode model [2], described by Eq. (1) through Eq. (7), to compute four sets of simulated I-V curves representing modules with either crystalline silicon and thin-film cells, and either good or poor performance. Figure 12 displays the I-V curves at STC; Table 1 lists the single diode model parameters for each module as well as each module's performance parameters at STC.

![Figure 12. I-V Curves at STC for simulated modules.](image-url)
Table 1. Parameters for simulated modules for method verification.

<table>
<thead>
<tr>
<th>Model Parameter</th>
<th>Module 1 cSi with good performance</th>
<th>Module 2 cSi with poor performance</th>
<th>Module 3 Thin-film with good performance</th>
<th>Module 4 Thin-film with poor performance</th>
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<tr>
<td>$I_{LO}$ (A)</td>
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<td>6.000</td>
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<td>500</td>
<td>200</td>
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<td>10</td>
<td>20</td>
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<td>0.0004</td>
</tr>
<tr>
<td>$N_s$</td>
<td>72</td>
<td>72</td>
<td>110</td>
<td>110</td>
</tr>
<tr>
<td>Performance parameter</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$I_{SC0}$ (A)</td>
<td>5.999</td>
<td>5.852</td>
<td>1.177</td>
<td>1.091</td>
</tr>
<tr>
<td>$V_{OC0}$ (V)</td>
<td>43.718</td>
<td>48.508</td>
<td>90.867</td>
<td>80.081</td>
</tr>
<tr>
<td>$I_{MP0}$ (A)</td>
<td>5.656</td>
<td>4.018</td>
<td>0.981</td>
<td>0.786</td>
</tr>
<tr>
<td>$V_{MP0}$ (V)</td>
<td>36.820</td>
<td>25.561</td>
<td>69.166</td>
<td>53.805</td>
</tr>
<tr>
<td>$P_{MP0}$ (W)</td>
<td>208.26</td>
<td>102.70</td>
<td>67.82</td>
<td>42.294</td>
</tr>
<tr>
<td>$FF$</td>
<td>0.794</td>
<td>0.362</td>
<td>0.634</td>
<td>0.484</td>
</tr>
<tr>
<td>$\beta_{Voc}$ (V/°C)(^1)</td>
<td>–0.180</td>
<td>–0.241</td>
<td>–0.245</td>
<td>–0.275</td>
</tr>
</tbody>
</table>

\(^1\) computed from simulated I-V curves with effective irradiance of 1000 W/m\(^2\); see [29] for method details.

We computed 28 I-V curves using 100 equally spaced voltage points and for environmental conditions consistent with IEC-61853-1 [35], i.e., combinations with effective irradiance of 100, 200, 400, 600 800, 1000 or 1100 W/m\(^2\), and cell temperatures of 15, 25, 50 or 75 °C. We include all 28 combinations of these quantities, obtaining a larger set of I-V curves than required by [35] which omits combinations of very high effective irradiance and low cell temperature, as well as combinations of very low effective irradiance and high cell temperature.

5.1.2 Recovery of parameters

We applied the parameter estimation method to each simulated module’s set of 28 I-V curves. Table 2 lists the error in each estimated parameter as a percent of its true value. Sufficient iterations were performed until parameter values did not change with more iterations.
Table 2. Estimation errors (percent) for model and performance parameters.

<table>
<thead>
<tr>
<th>Model Parameter</th>
<th>Module 1 cSi with good performance</th>
<th>Module 2 cSi with poor performance</th>
<th>Module 3 Thin-film with good performance</th>
<th>Module 4 Thin-film with poor performance</th>
</tr>
</thead>
<tbody>
<tr>
<td>$I_{L0}$ (A)</td>
<td>5.0E–5</td>
<td>0.042</td>
<td>0.019</td>
<td>0.17</td>
</tr>
<tr>
<td>$I_{O0}$ (nA)</td>
<td>–0.64</td>
<td>–4.1</td>
<td>–16.4</td>
<td>–38.8</td>
</tr>
<tr>
<td>$n_0$</td>
<td>–0.029</td>
<td>–0.21</td>
<td>–0.84</td>
<td>–2.6</td>
</tr>
<tr>
<td>$R_{S10}$ (Ω)</td>
<td>–0.28</td>
<td>–3.5</td>
<td>–0.43</td>
<td>–0.9</td>
</tr>
<tr>
<td>$R_{S0}$ (Ω)</td>
<td>0.12</td>
<td>0.023</td>
<td>0.86</td>
<td>1.4</td>
</tr>
<tr>
<td>$E_{g0}$ (eV)</td>
<td>0.032</td>
<td>0.23</td>
<td>0.93</td>
<td>2.7</td>
</tr>
<tr>
<td>Performance parameter</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$I_{SC0}$ (A)</td>
<td>–3.3E–5</td>
<td>–0.047</td>
<td>–6.4E–3</td>
<td>–0.039</td>
</tr>
<tr>
<td>$V_{OC0}$ (V)</td>
<td>0.028</td>
<td>0.20</td>
<td>0.82</td>
<td>2.5</td>
</tr>
<tr>
<td>$I_{M0}$ (A)</td>
<td>–5.8E–4</td>
<td>0.10</td>
<td>–0.11</td>
<td>–0.74</td>
</tr>
<tr>
<td>$V_{M0}$ (V)</td>
<td>0.028</td>
<td>0.24</td>
<td>0.91</td>
<td>3.2</td>
</tr>
<tr>
<td>$P_{M0}$ (W)</td>
<td>0.028</td>
<td>0.35</td>
<td>0.80</td>
<td>2.4</td>
</tr>
<tr>
<td>FF</td>
<td>–3.9E–4</td>
<td>0.19</td>
<td>–0.019</td>
<td>–0.09</td>
</tr>
<tr>
<td>Iterations</td>
<td>100</td>
<td>500</td>
<td>500</td>
<td>500</td>
</tr>
</tbody>
</table>

Estimation errors for both model and performance parameters decrease by orders of magnitude (Table 3) when the estimated value for $n$ is replaced by its exact value in the subsequent parameter estimates. As described in Appendix D, estimation of the diode factor relies on a simplification of the single diode equation. The error inherent in this simplification propagates to errors in the values for other parameters, and the magnitudes of these errors generally increase as the magnitude of the error in the diode factor increases.
Table 3. Estimation errors (percent) for model and performance parameters when using exact diode factor.

<table>
<thead>
<tr>
<th>Model Parameter</th>
<th>Module 1 cSi with good performance</th>
<th>Module 2 cSi with poor performance</th>
<th>Module 3 Thin-film with good performance</th>
<th>Module 4 Thin-film with poor performance</th>
</tr>
</thead>
<tbody>
<tr>
<td>$I_{L0}$ (A)</td>
<td>-1.4E-8</td>
<td>-3.7E-8</td>
<td>2.8E-8</td>
<td>-9.4E-9</td>
</tr>
<tr>
<td>$I_{O0}$ (nA)</td>
<td>3.5E-7</td>
<td>2.4E-5</td>
<td>2.9E-7</td>
<td>-6.5E-7</td>
</tr>
<tr>
<td>$R_{Si0}$ (Ω)</td>
<td>1.9E-4</td>
<td>2.7E-3</td>
<td>1.9E-7</td>
<td>-5.5E-7</td>
</tr>
<tr>
<td>$R_{S0}$ (Ω)</td>
<td>3.7E-5</td>
<td>1.7E-3</td>
<td>2.1E-7</td>
<td>-1.0E-6</td>
</tr>
<tr>
<td>$E_{g0}$ (eV)</td>
<td>8.1E-4</td>
<td>8.1E-4</td>
<td>8.1E-4</td>
<td>8.1E-4</td>
</tr>
<tr>
<td>Performance parameter</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$I_{SC0}$ (A)</td>
<td>1.7E-8</td>
<td>1.9E-5</td>
<td>2.5E-8</td>
<td>3.5E-8</td>
</tr>
<tr>
<td>$V_{OC0}$ (V)</td>
<td>4.7E-8</td>
<td>4.5E-6</td>
<td>-1.0E-8</td>
<td>1.9E-8</td>
</tr>
<tr>
<td>$I_{MP0}$ (A)</td>
<td>-1.2E-6</td>
<td>-1.0E-3</td>
<td>2.7E-5</td>
<td>-2.3E-5</td>
</tr>
<tr>
<td>$V_{MP0}$ (V)</td>
<td>1.3E-6</td>
<td>-2.7E-4</td>
<td>-2.7E-5</td>
<td>2.3E-5</td>
</tr>
<tr>
<td>$P_{MP0}$ (W)</td>
<td>1.0E-7</td>
<td>-1.3E-3</td>
<td>1.0E-8</td>
<td>1.6E-7</td>
</tr>
<tr>
<td>$FF$</td>
<td>3.8E-8</td>
<td>-1.3E-3</td>
<td>-6.5E-0</td>
<td>1.1E-7</td>
</tr>
<tr>
<td>Iterations</td>
<td>100</td>
<td>100</td>
<td>100</td>
<td>100</td>
</tr>
</tbody>
</table>

5.2. Validation

We obtained a total of 951 I-V curves from a 96-cell monocrystalline silicon module measured on a two-axis tracker in Albuquerque, NM. Effective irradiance was measured in the module’s plane with a reasonably well-matched reference cell. Prior testing of this module established the following parameters:

- $\alpha_{Isc} = 0.002 \text{ A/°C}$
- $\beta_{Voc} = 0.187 \text{ V/°C}$

Cell temperature was estimated from measured $V_{OC}$ and $I_{SC}$ using an equivalent cell temperature method (e.g., [36]).

We divided the data into one set of 205 I-V curves for model estimation, and then predicted the performance of the module for the remaining 746 I-V curves. Figure 13 shows the environmental conditions for the whole data set and the subset selected for model fitting. Figure 14 displays the error (percent) in values calculated by Eq. (1) using the five coefficient values resulting from fitting Eq. (1) to each of the in-sample I-V curves. The very small errors (Figure 14) confirm that each I-V curve’s data is being fit quite well by the fitting algorithm described in Section 4.2 Step 2 and Step 3. The model parameter values resulting from Section 4.2 Step 4 are summarized in Table 4.
Figure 13. Irradiance and temperature conditions for model validation.

Figure 14. Error (percent) in performance parameters for fitted I-V curves.
Table 4. Estimated model parameters for validation data.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\alpha_{ac}$ (A/°C)</td>
<td>0.0020</td>
<td>$I_{\infty}$ (nA)</td>
<td>1.067</td>
</tr>
<tr>
<td>$\beta_{Voc}$ (V/°C)</td>
<td>-0.1871</td>
<td>$E_{g0}$ (eV)</td>
<td>0.9177</td>
</tr>
<tr>
<td>$N_s$</td>
<td>96</td>
<td>$R_{sH0}$ (Ω)</td>
<td>327.2</td>
</tr>
<tr>
<td>$n$</td>
<td>1.170</td>
<td>$R_{s0}$ (Ω)</td>
<td>0.4827</td>
</tr>
<tr>
<td>$I_{L0}$ (A)</td>
<td>5.965</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

We next predicted module performance for the conditions corresponding to each of the 746 out-of-sample I-V curves. Figure 15 compares measured voltage and current to predictions made with the model parameters listed in Table 4. The model is generally successful at predicting voltage and current over a wide range of conditions. However, Figure 16 shows relative prediction error for each quantity in Figure 15 and reveals that the model is more successful predicting $I_{MP}$ at high irradiance than at low irradiance, as well as the presence of biases in predicted $I_{MP}$ and $I_{SC}$. Predicted $P_{MP}$, and relative error in predicted $P_{MP}$ are displayed in Figure 17 and show that the bias in predicted $I_{MP}$ conveys directly to bias in predicted $P_{MP}$. Because each I-V curve used for parameter estimation is fitted accurately (Figure 14) the biases evident in Figure 16 and Figure 17 indicate deficiencies in the single diode model rather than in the parameter fitting algorithm.

![Figure 15. Predicted vs. measured voltage and current.](image-url)
Figure 16. Relative error (percent) in predicted voltage and current.
Figure 17. Predicted vs. measured power and relative error in predicted power.
6. SUMMARY

We have presented a new method for estimating parameters for single diode models, illustrated by application to the single diode model specified in [2]. The method requires prior determination of module temperature coefficients for $I_{SC}$ and $V_{OC}$ and a set of I-V curves measured across a range of effective irradiance and cell temperature. The method first estimates the diode factor from measured $V_{OC}$ for a set of I-V curves, applies an iterative procedure to obtain values for $I_L$, $I_O$, $R_{SH}$, and $R_S$ for each I-V curve, and finally, obtains parameters for the single diode model by a series of regressions.

We applied our method to recover parameters from I-V curves that were computed from several assumed sets of parameters for a single diode model to verify the method’s robustness. Being a sequential estimation algorithm, values for $I_L$, $I_O$, $R_{SH}$, and $R_S$ for each fitted I-V curve are conditional on the value for the diode factor $n$. As demonstrated in Section 5.1, small errors in the recovered diode factor can result in significant differences in the values for the other parameters. The diode factor is estimated using a linear relationship (Eq. (22)) which is an approximation derived from the single diode equation (see Appendix D). We have observed that the other parameters for an I-V curve are quite sensitive to small changes in the diode factor. Consequently our method’s robustness may be improved by additional refinement of the technique for recovering the diode factor.

Our method involves numerical convergence at a number of steps. However, the initial values for the optimizations are not selected with randomness, and hence, subject to variation in machine precision and software (e.g., Matlab versions) we believe our method to be reliable.

Having outlined the method in detail we believe it to be accessible to one with an adequate mathematical and engineering background. However, we believe that the method, as described in this report, yet offers opportunities for simplification. For example, the initial estimate of $R_{SH}$ requires a fairly involved set of calculations (i.e., coordinate transformations, spline fitting and numerical integration) yet the initial estimate of $R_{SH}$ is later replaced with an updated value (see Section 4.2 Step 3c). Consequently, a less accurate initial estimate obtained by a simpler process may be just as good. We tested some simpler methods, e.g., Eq. (8) (see Appendix E) and found that most of the resulting values led to suitable values for all parameters. However the alternative methods also increased somewhat the number of I-V curves for which the parameter estimation failed and so we have retained the more complicated technique. We view the complexity involved in the initial estimate of $R_{SH}$ as indicating an opportunity to improve our algorithm.
7. REFERENCES


27. (IEC), I.E.C., 60891 Ed. 2.0: Photovoltaic devices - Procedures for temperature and irradiance corrections to measured I-V characteristics, 2010, IEC.
35. (IEC), I.E.C., 61853-1 Ed. 1.0: Photovoltaic (PV) module performance testing and energy rating - Part I: Irradiance and temperature performance measurements and power rating, 2011.
36. (IEC), I.E.C., 60904-5 Ed. 2.0: Photovoltaic devices - Part 5: Determination of the equivalent cell temperature (ECT) of photovoltaic (PV) devices by the open-circuit voltage method, 2011.
Lambert’s W function is the solution $W = W(x)$ of the equation $x = W \exp(W)$. An equation of the form

$$p^{ax+b} = cx + d \quad (A1)$$

can be transformed by the substitution

$$-t = ax + \frac{ad}{c} \quad (A2)$$

to

$$tp' = -\frac{a}{c} p^{\frac{b-ad}{c}} \quad (A3)$$

By the definition of Lambert’s W, we obtain

$$t = \frac{W\left(-\frac{a}{c} p^{\frac{b-ad}{c}} \ln p\right)}{\ln p} \quad (A4)$$

which leads to a solution of Eq. (A1) in terms of Lambert’s W function:

$$x = \frac{1}{a \ln p} W\left(-\frac{a}{c} p^{\frac{b-ad}{c}} \ln p\right) - \frac{d}{c} \quad (A5)$$

Considering $I = I(V)$ and applying this process to the single diode equation (Eq. (1)), we obtain

$$I = I_L - I_O \left[ \exp\left( \frac{V + IR_s}{nV_{th}} \right) - 1 \right] - \frac{V + IR_s}{R_{SL}}$$

$$\exp\left( \frac{R_s}{nV_{th}} \cdot I + \frac{V}{nV_{th}} \right) = -\frac{R_{SL} + R_s}{I_O R_{SL}} \cdot I + \frac{(I_L + I_O) R_{SL}}{I_O R_{SL}} - \frac{V}{R_{SL}} \quad (A6)$$

which after using Eq. (A5) simplifies to Eq. (9) A similar process yields Eq. (10).
Because Lambert’s $W$ is intimately related to the exponential function, derivatives and integrals of expressions involving Lambert’s $W$ often can be expressed again in terms of Lambert’s $W$. Several of these identities are needed for our analysis:

\[
\frac{dW(x)}{dx} = \frac{W(x)}{x(1+W(x))} \quad (A7)
\]

\[
\int W(x)\,dx = x \left[W(x) - 1 + \frac{1}{W(x)}\right] + C \quad (A8)
\]

\[
\int \frac{W(x)}{x}\,dx = \frac{1}{2}(1+W(x))^2 + C \quad (A9)
\]

\[
\int W\left(\alpha \exp\left(\frac{x+\beta}{\delta}\right)\right)\,dx = \frac{\delta}{2}\left(1+\alpha \exp\left(\frac{x+\beta}{\delta}\right)\right)^2 + C \quad (A10)
\]

The substitution $u = \alpha \exp\left(\frac{x+\beta}{\delta}\right)$ changes the integral in Eq. (A10) into the form of Eq. (A9), from which the right side of Eq. (A10) is obtained.
APPENDIX B: NUMERICAL EVALUATION OF LAMBERT’S W FUNCTION

We evaluate the principal branch of the Lambert’s W function $W_0(x)$ using the following iterative scheme. Steps 1 and 2 are in common use (e.g., implemented in Matlab as lambertw.m); Step 3 is our own innovation.

1. An initial value $w_0 \approx W(x)$ is obtained from asymptotic expansions ([23], Eq. 4.18 and Eq. 4.22):

   $$w_0 = \begin{cases} 
   \log x - \log (\log x) & x > 1.5 - 1/e \approx 1.13 \\
   \sqrt{2ex + 2} & x \leq 1.5 - 1/e 
   \end{cases} \quad (B1)$$

2. Values are updated until convergence using Halley’s method ([23], Eq. 5.9):

   $$w_{i+1} = w_i - \frac{w_i \exp w_i - x}{\exp w_i (w_i + 1) - \frac{(w_i + 2)(w_i \exp w_i - x)}{2w_i + 2}} \quad (B2)$$

3. In application to the single diode equation the argument $x$ frequently exceeds the largest floating point value allowed (e.g., for 64-bit Matlab, around $10^{308}$. To compute values for $W_0(x)$ for a large argument $x$ we find the solution $w$ to

   $$w + \log w = x \quad (B3)$$

   which results from taking the logarithm of both sides of $x = w \exp w$. We apply Newton’s method [32] using an initial guess $w_0 = \log x$. Set $g(y) = w + \log w - y = 0$; root-finding by Newton’s method, i.e., $y_{i+1} = y_i - \frac{g}{g'}$, leads to

   $$w_{i+1} = w_i \frac{1 - \log w_i + \log x}{1 + w_i} \quad (B4)$$

Three iterations of Eq. (B4) suffice to obtain eight digits of precision.
APPENDIX C: I-V CURVE FITTING USING THE CO-CONTENT INTEGRAL

C.1. Relationship between the co-content and the five parameters.

Here we define the co-content integral and demonstrate the relationship between the co-content integral and the parameters for the single diode equation (Eq. (1)). This relationship was first published by [6]; we provide here additional details regarding the derivation of the equations presented in [6] and comment on several challenges presented by the method described in [6]. We differ from [6] by setting the sign on current flow as indicated Figure 1 to obtain Eq. (1); [6] reverses the sign on the current flow.

Define the co-content \( CC = CC(V) \) by

\[
CC(V) = \int_0^V (I_{sc} - I(\eta)) \, d\eta
\]  

(C1)

In [6] the definition is given as \( CC(V) = \int_0^V (I(\eta) - I_{sc}) \, d\eta \) because the single diode equation is also given in [6] using active rather than passive sign convention. Figure C1 illustrates the co-content function.

Figure C1. Illustration of co-content integral.
The co-content function \( CC(V) \) can be expressed exactly as a polynomial in \( V \) and \( I = I(V) \). Begin with Eq. (9):

\[
I = \frac{R_{SH}}{R_{SH} + R_S}(I_L + I_O) - \frac{V}{R_{SH} + R_S} - \frac{nV_{th}}{R_S} W\left(\frac{R_S I_O}{nV_{th}}, \frac{R_{SH}}{R_{SH} + R_S} - \frac{R_S}{R_{SH} + R_S} \left(I_L + I_O + \frac{R_{SH} - R_S}{nV_{th}} \right) \right)
\]  

(C2)

Substituting \( \eta \) (the variable of integration in Eq. (C1)) for \( V \) in Eq. (C2) and for convenience, abbreviating

\[
W\left(\frac{R_S I_O}{nV_{th}}, \frac{R_{SH}}{R_{SH} + R_S} - \frac{R_S}{R_{SH} + R_S} \left(I_L + I_O + \frac{R_{SH} - R_S}{nV_{th}} \right) \right) = W\left(A \exp\left(\frac{\eta + B}{C}\right)\right)
\]  

(C3)

where \( A = \frac{R_S I_O}{nV_{th} R_{SH} + R_S} \), \( B = R_S (I_L + I_O) \) and \( C = \frac{(R_{SH} + R_S)nV_{th}}{R_{SH}} \), from Eq. (C1) we obtain:

\[
CC(V) = \int_0^V \left(I_{SC} - I(\eta)\right)d\eta
\]

\[
= \int_0^V \left(I_{SC} - \frac{R_{SH}}{R_{SH} + R_S} (I_L + I_O) - \frac{V}{R_{SH} + R_S} - \frac{nV_{th}}{R_S} W\left(A \exp\left(\frac{\eta + B}{C}\right)\right) \right) d\eta
\]

\[
= \left(I_{SC} - \frac{R_{SH}}{R_{SH} + R_S} (I_L + I_O)\right) - \frac{V^2}{2(R_{SH} + R_S)}
\]

\[
- \frac{nV_{th}}{2R_S} A \left[1 + W\left(A \exp\left(\frac{V + B}{C}\right)\right)\right]^2 - \left(1 + W\left(A \exp\left(\frac{B}{C}\right)\right)\right)^2
\]

(C4)

using Eq. (A10). The variable \( I \) is re-introduced in Eq. (C4) by replacing the Lambert’s \( W \) functions using Eq. (C2):

\[
W\left(A \exp\left(\frac{V + B}{C}\right)\right) = \frac{R_S}{nV_{th}} \left[I - \frac{R_{SH}}{R_{SH} + R_S} (I_L + I_O) + \frac{V}{R_{SH} + R_S} \right]
\]  

(C5)

\[
W\left(A \exp\left(\frac{B}{C}\right)\right) = \frac{R_S}{nV_{th}} \left[I_{SC} - \frac{R_{SH}}{R_{SH} + R_S} (I_L + I_O) \right]
\]  

(C6)

Substituting Eq. (C5) and Eq. (C6) into Eq. (C4), after manipulation many terms cancel, yielding at the end
\[ CC(V) = \int_0^V \left( I_{SC} - I(\eta) \right) d\eta \]
\[ = \frac{1}{2R_{SH}} V^2 + \frac{R_S \left( R_{SH} + R_S \right)}{2R_{SH}} (I_{SC} - I)^2 - \frac{R_S}{R_{SH}} (I_{SC} - I)V \]
\[ + \frac{R_{SH} + R_S}{R_{SH}} I_{SC} - (I_L + I_o) - \frac{nVth}{R_{SH}} ]V \]
\[ + \left[ R_S (I_L + I_o - I_{SC}) - \frac{R_S^2}{R_{SH}} I_{SC} - \frac{R_S}{R_{SH}} + \frac{R_S}{R_{SH}} nVth \right] (I_{SC} - I) \]

Eq. (C7) expresses the co-content function as a 2nd order polynomial in \( V \) and \( I_{SC} - I \):

\[ CC(V) = c_1 V + c_1 (I_{SC} - I) + c_{V1} (I_{SC} - I)V + c_{V2} V^2 + c_{V3} (I_{SC} - I)^2 \]
\[ = \begin{bmatrix} V & I_{SC} - I & V (I_{SC} - I) & V^2 & (I_{SC} - I)^2 \end{bmatrix} \begin{bmatrix} c_V & c_I & c_{V1} & c_{V2} & c_{V3} \end{bmatrix}^T \]

As described in [6] values for the coefficients \( \beta \) in Eq. (C8) may be determined by regressing \( CC(V) \) computed by numerical integration over the range \([0 \ V_{OC}]\) for an I-V curve onto the terms indicated in Eq. (C8). The coefficients thus obtained may be related to the values for the parameters for the single diode equation describing the I-V curve, e.g.:

\[ R_{SH} = \frac{1}{2c_{2V}} = \frac{1}{2\beta_4} \]
\[ R_S = \frac{\sqrt{1 + 16c_{2V}c_{2I} - 1}}{4c_{2V}} \]
\[ = \frac{\sqrt{1 + 16\beta_4\beta_5 - 1}}{4\beta_4} \]

\[ \text{C.2. Improvements to the regression method.} \]

The principal weakness of this method for estimating parameters for the single diode equation from data lies in the multicolinearity of the predictors in Eq. (C8). Multicolinearity can be indicated when predictors are highly correlated: Table C1 shows correlations among the predictors for the measured I-V curve displayed in Figure 2. When multicolinearity is present the values of the regression coefficients can become quite sensitive to small changes in the predictor and predicted values or to the numerical procedure used for matrix inversion [37]. Consequently, when applying Eq. (C8) through Eq. (C10) to measured I-V curves we frequently observed numerical problems [31], e.g., imaginary values for \( R_S \) resulting from a negative value for the coefficient \( c_{2I} \).
Table C1. Correlation coefficients for predictors in Eq. C8.

<table>
<thead>
<tr>
<th></th>
<th>$V$</th>
<th>$I_{sc} - I$</th>
<th>$V(I_{sc} - I)$</th>
<th>$V^2$</th>
<th>$(I_{sc} - I)^2$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V$</td>
<td>1.000</td>
<td>0.626</td>
<td>0.609</td>
<td>0.968</td>
<td>0.484</td>
</tr>
<tr>
<td>$I_{sc} - I$</td>
<td>0.626</td>
<td>1.000</td>
<td>0.999</td>
<td>0.750</td>
<td>0.954</td>
</tr>
<tr>
<td>$V(I_{sc} - I)$</td>
<td>0.609</td>
<td>0.999</td>
<td>1.000</td>
<td>0.734</td>
<td>0.964</td>
</tr>
<tr>
<td>$V^2$</td>
<td>0.968</td>
<td>0.750</td>
<td>0.734</td>
<td>1.000</td>
<td>0.601</td>
</tr>
<tr>
<td>$(I_{sc} - I)^2$</td>
<td>0.484</td>
<td>0.954</td>
<td>0.964</td>
<td>0.601</td>
<td>1.000</td>
</tr>
</tbody>
</table>

We observed that the coefficients in Eq. (C8) are quite sensitive to small deviations in $CC(V)$ resulting from the numerical integration procedures. For example, a simple trapezoid rule applied to compute $CC(V)$ will produce biased values because the I-V curve is generally concave downward (Figure C1), and hence the values computed by a trapezoid rule will be negatively biased. The biased values in turn affect the coefficients indicated in Eq. (C8).

Multicollinearity among predictors may be remedied by a number of different techniques. We attempted several, including: standardizing the predictors, dropping predictors from the model, ridge regression, and principal components transformations involving several or all of the predictors. Among these methods we found that a principal components transformation of the predictors $V$ and $I_{sc} - I$ yielded more reliable results than other methods, as judged by the agreement between the fitted single diode equation and the data, and the frequency of obtaining reasonable parameter values from I-V curve data without visible flaws (e.g., increasing current with increasing voltage). However, none of the methods we explored resulted in reasonable coefficient values for most I-V curves for each of a set of modules with diverse characteristics.

We use a modified version of the approach from [6] only to obtain an initial estimate of $R_{SH}$. We modified the method in [6] to include the following steps:

1. Fit a quadratic spline $S(V)$ to the I-V curve data $(V_k, I_k), k = 0, \ldots, N$, where $(V_0, I_0) = (0, I_{sc})$ and $(V_N, I_N) = (V_{oc}, 0)$ using a technique [38] that preserves the monotonicity and convexity expected in the I-V curve. Ideally the data describing a measured I-V curve are monotonic decreasing and concave downward. Compute $CC_k = CC(V_k)$ by exact integration of the quadratic spline $S(V)$ fitted in Step 1. Because the spline fit is more sensitive to data variation at the ends of the I-V curve data (i.e., near $I_{sc}$ and $V_{oc}$, e.g., for $0 \leq k < 5$ and $N - 5 \leq k \leq N$) a trapezoid rule is used to compute $CC_k$ for these intervals.

2. Standardize the predictors $V$ and $II = I_{sc} - I$ by shifting and scaling to obtain

$$\hat{V}_k = \frac{V_k - \mu_V}{\sigma_V}$$

and
\[ \hat{H}_k = \frac{H_k - \mu_H}{\sigma_H} \]  
(C12)

which have zero mean and unit standard deviation, and shifting \( CC \) to have zero mean:

\[ \hat{CC}_k = CC_k - \mu_{CC} \]  
(C13)

3. Compute a principal components transformation \( W \) to transform \( [\hat{V} \quad \hat{H}] \) to principal components \( [X \quad Y] = [\hat{V} \quad \hat{H}]W \). The matrix \( W \) is an orthogonal linear transformation from \( \mathbb{R}^2 \) to \( \mathbb{R}^2 \) and thus is invertible. Calculate the remaining predictors \( XY = X \circ Y \), \( X^2 = X \circ X \) and \( Y^2 = Y \circ Y \) for the full quadratic model

\[ \hat{CC} = \gamma_1 X + \gamma_2 Y + \gamma_3 XY + \gamma_4 X^2 + \gamma_5 Y^2 + \gamma_6 \]

\[ = [X \ 1] \gamma \]  
(C14)

where \( \gamma = [\gamma_1 \ \gamma_2 \ \gamma_3 \ \gamma_4 \ \gamma_5 \ \gamma_6]^T \), then regress \( \hat{CC} \) onto the predictors to obtain values for the coefficients \( \gamma_i \).

4. Transform the coefficients \( \gamma \) to obtain the coefficients \( \beta = [c_v \ c_v \ c_{2v} \ c_{2v}] \) for Eq. (C8) (see below).

5. Extract a value for \( R_{SHR} \) from \( \beta \) using Eq. (C9).

The transformation in Step 4 can be obtained by setting Eq. (C14) equal to Eq. (C8)

\[ \hat{CC} = CC - \mu_{CC} = [X \ 1] \gamma \]

\[ = [V \ I_{SC} - I \ V(I_{SC} - I) \ V^2 \ (I_{SC} - I)^2] \beta - \mu_{CC} \]  
(C15)

and solving Eq. (C15) for \( \beta \) by using a matrix left inverse, i.e., \( H_{\text{left}}^{-1} = (H^T H)^{-1} H^T \ :

\[ \beta = [V \ I_{SC} - I \ V(I_{SC} - I) \ V^2 \ (I_{SC} - I)^2]_{\text{left}}^{-1} ([X \ 1] \gamma + \mu_{CC}) \]  
(C16)

However we found a computationally simpler approach that yielded more reliable values for \( R_{SHR} \) which is the objective of the regression algorithm. Using Eq. (C11) and Eq. (C12) we obtain

\[ [V \ I_{SC} - I \ V(I_{SC} - I) \ V^2 \ (I_{SC} - I)^2] = [\hat{V} \ \hat{H} \ \hat{V} \circ \hat{H} \ \hat{V}^2 \ \hat{H}^2] A + M \]  
(C17)

where
\[
A = \begin{bmatrix}
\sigma_y & 0 & \sigma_y \mu_y & 2\sigma_y \mu_y & 0 \\
0 & \sigma_y & \sigma_y \mu_y & 0 & 2\sigma_y \mu_y \\
0 & 0 & \sigma_y \sigma_y \mu_y & 0 & 0 \\
0 & 0 & 0 & \sigma_y^2 & 0 \\
0 & 0 & 0 & 0 & \sigma_y^2 \\
\end{bmatrix}
\]

and

\[
M = \begin{bmatrix}
\mu_y & \mu_y & \mu_y \mu_y & \mu_y^2 & \mu_y^2 \\
\end{bmatrix}
\]

Also, from \( [X \ Y] = \begin{bmatrix} \hat{V} & \hat{H} \end{bmatrix} \) we obtain

\[
\begin{bmatrix} X & Y & X \circ T & X^2 & Y^2 \end{bmatrix} = \begin{bmatrix} \hat{V} & \hat{H} & \hat{V} \circ \hat{H} & \hat{V}^2 & \hat{H}^2 \end{bmatrix} B
\]

where

\[
B = \begin{bmatrix}
0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 \\
\end{bmatrix}
\]

From Eq. (C8),

\[
\mu_{cc} = \text{mean}(CC)
= (c_y \mu_y + c_y \mu_y + c_y \mu_y \mu_y + c_y \mu_y^2 + c_y \mu_y^2)
+ (c_y \mu_y \mu_y + c_y \mu_y^2 + c_y \mu_y^2)
= \mathbf{M} \mathbf{B} + \Delta
\]

Combining these expressions starting with Eq. (C15)

\[
\hat{C}C = CC - \mu_{cc}
= \begin{bmatrix} \hat{V} & I_{sc} - I \end{bmatrix} V^2 \left(I_{sc} - I\right)^2 \mathbf{B} - \mu_{cc}
= \begin{bmatrix} \hat{V} & \hat{H} & \hat{V} \circ \hat{H} & \hat{V}^2 & \hat{H}^2 \end{bmatrix} \mathbf{A} + \mathbf{M} \mathbf{B} - \mu_{cc}
= \begin{bmatrix} X & Y & X \circ T & X^2 & Y^2 \end{bmatrix} \mathbf{B}^{-1} \mathbf{A} \mathbf{B} - \Delta
\]

Consequently
\[ [X \ 1]y = [X \ Y \ X^\circ T \ X^2 \ Y^2] [\begin{bmatrix} \gamma_1 \\ \gamma_2 \\ \gamma_3 \\ \gamma_4 \\ \gamma_5 \end{bmatrix}]^T + \gamma_6 \]

\[ = [X \ Y \ X^\circ T \ X^2 \ Y^2] \mathbf{B}^{-1} \mathbf{A} \mathbf{\beta} - \Delta \]

and in our implementation we set

\[ \mathbf{\beta} = \left( \mathbf{B}^{-1} \mathbf{A} \right)^{-1} [\begin{bmatrix} \gamma_1 \\ \gamma_2 \\ \gamma_3 \\ \gamma_4 \\ \gamma_5 \end{bmatrix}]^T \]
Here, we show that Eq. (D1), relating $V_{OC}$ to $\ln(E/E_0)$, derives from a simplification to the single diode equation.

$$V_{OC} - V_{OC0} \approx nV_{th} \ln \left( E/E_0 \right)$$  \hfill (D1)

Denote reference conditions and parameters at reference conditions by the subscript $\sim_0$. From Eq. (10) we have

$$V_{OC} = (I_L + I_O) R_{SH} - nV_{th} W \left( \frac{I_O R_{SH}}{nV_{th}} \exp \left( \frac{(I_L + I_O) R_{SH}}{nV_{th}} \right) \right)$$  \hfill (D2)

and at reference conditions:

$$V_{OC0} = (I_{L0} + I_{O0}) R_{SH0} - nV_{th0} W \left( \frac{I_{O0} R_{SH0}}{nV_{th0}} \exp \left( \frac{(I_{L0} + I_{O0}) R_{SH0}}{nV_{th0}} \right) \right)$$  \hfill (D3)

The argument of the $W$ function in Eq. (D2) is extremely large due to the factor $\exp \left( \frac{(I_L + I_O) R_{SH}}{nV_{th}} \right)$, e.g., $\exp \left( \frac{6A \times 200\Omega}{1.1 \times 2V} \right) = \exp(550)$ which results when substituting coefficient values representative of a 72-cell cSi module. Therefore we may approximate $W(x) \sim \ln x - \ln \ln x \approx \ln x$ [23] and obtain from Eq. (D2)

$$V_{OC} \approx (I_L + I_O) R_{SH} - nV_{th} \ln \left( \frac{I_O R_{SH}}{nV_{th}} \right) + \left( \frac{(I_L + I_O) R_{SH}}{nV_{th}} \right)$$  \hfill (D4)

$$= -nV_{th} \ln \left( \frac{I_O R_{SH}}{nV_{th}} \right)$$

and from Eq. (D3)

$$V_{OC0} \approx -nV_{th0} \ln \left( \frac{I_{O0} R_{SH0}}{nV_{th0}} \right)$$  \hfill (D5)

Setting $T_c = T_0$ (i.e., the cells are at the selected reference temperature), we have $V_{th} = V_{th0}$ and $I_O \approx I_{O0}$ (from Eq. (3)) so Eq. (D4) and Eq. (D5) lead to
\[ V_{OC} - V_{OC0} \approx -nV_{th0} \ln \left( \frac{I_{00}R_{SH}}{nV_{th0}} \right) + nV_{th0} \ln \left( \frac{I_{00}R_{SH0}}{nV_{th0}} \right) \]

\[ = nV_{th0} \ln \left( \frac{R_{SH0}}{R_{SH}} \right) \]

\[ = nV_{th0} \ln \left( \frac{E}{E_0} \right) \]

where the last line results from Eq. (5): \( R_{SH} = \frac{R_{SH0}E_0}{E} \). Eq. (5) is specific to the single diode model in [2], and the relationship in Eq. (D1) should also be established for other single diode models (e.g., PVsyst [1]) that use different relationships between \( R_{SH} \) and \( E \).
APPENDIX E: EVALUATION OF APPROXIMATIONS IN THE SINGLE DIODE EQUATION

We considered several simplifications to the single diode equation which are obtained by substituting approximations for $I_L$ or $R_{SH}$ in order to reduce the number of parameters to be estimated. We found that, in each case considered, the approximations led to unreasonably small values for $R_S$.

**Approximations for $I_L$.**

It is common to approximate $I_L$ as $I_L \approx I_{SC}$ or as $I_L \approx (1 + R_S/R_{SH})I_{SC}$ either of which effectively replace the unknown parameter $I_L$ with the measured value of $I_{SC}$. However, these substitutions are analytically equivalent to assuming that $R_S = 0$ in the first case or that $R_S$ is unreasonably small or negative in the second case. Consequently we do not recommend use of these simplifications.

Eq. (10) may be re-arranged to obtain an expression for $R_S$ at $I = I_{SC}$:

$$\begin{align*}
R_S &= \frac{I_L + I_O - I_{SC}R_{SH}}{I_{SC}} - nV_{th}W \left( \frac{I_O R_{SH}}{nV_{th}} \exp \left( \frac{(I_L + I_O - I_{SC})R_{SH}}{nV_{th}} \right) \right) \\
&= \left(1 + \frac{R_S}{R_{SH}}\right)I_{SC} - nV_{th}W \left( \frac{I_O R_{SH}}{nV_{th}} \exp \left( \frac{(R_S/R_{SH})I_{SC} + I_O R_{SH}}{nV_{th}} \right) \right)
\end{align*}$$

(E1)

Substituting $I_L = \left(1 + \frac{R_S}{R_{SH}}\right)I_{SC}$ leads to

$$R_S = \frac{(R_S/R_{SH})I_{SC} + I_O R_{SH}}{I_{SC}} - nV_{th}W \left( \frac{I_O R_{SH}}{nV_{th}} \exp \left( \frac{(R_S/R_{SH})I_{SC} + I_O R_{SH}}{nV_{th}} \right) \right)$$

(E2)

$$= R_S + \frac{R_S I_{SC} + R_{SH} I_O}{I_{SC}} - nV_{th}W \left( \frac{I_O R_{SH}}{nV_{th}} \exp \left( \frac{R_S I_{SC} + R_{SH} I_O}{nV_{th}} \right) \right)$$

and in turn

$$\frac{R_{SH} I_O}{nV_{th}} = W \left( \frac{I_O R_{SH}}{nV_{th}} \exp \left( \frac{R_S I_{SC} + R_{SH} I_O}{nV_{th}} \right) \right)$$

(E3)

Applying the definition of Lambert’s W function to Eq. (E3) obtains

$$\frac{R_{SH} I_O}{nV_{th}} \exp \left( \frac{R_{SH} I_O}{nV_{th}} \right) = \frac{I_O R_{SH}}{nV_{th}} \exp \left( \frac{R_S I_{SC} + R_{SH} I_O}{nV_{th}} \right)$$

(E4)

which implies $R_S I_{SC} = 0$ and in turn $R_S = 0$. 
Setting $I_L \approx I_{SC}$ leads to unreasonably small values for $R_s$. Substituting $I_L = I_{SC}$ into the single diode equation at $I = I_{SC}$ (Eq. (1)):

$$0 = I_o - I_o \exp \left( \frac{I_{SC} R_s}{nV_{th}} \right) - \frac{I_{SC} R_s}{R_{SH}}$$

(E5)

leads to

$$- \frac{I_{SC}}{R_{SH} I_o} R_s + 1 = \exp \left( \frac{I_{SC}}{nV_{th}} R_s \right)$$

(E6)

which can be solved for $R_s$ using the transformation indicated by Eq. (A2):

$$R_s = W \left( \frac{I_o R_{SH}}{nV_{th}} \exp \left( \frac{I_o R_{SH}}{nV_{th}} \right) \right)$$

(E7)

Reasonable values for $I_o$ and $R_{SH}$ lead to $I_o R_{SH} \sim 10^{-8} \times 10^3 = 10^{-5}$ which in turn results in

$$R_s = W \left( \frac{I_o R_{SH}}{nV_{th}} \exp \left( \frac{I_o R_{SH}}{nV_{th}} \right) \right) \sim W \left( 10^{-5} \times 1 \right) \sim 10^{-5}$$

which is far too small to be reasonable.

**Approximation for $R_{SH}$**

If we approximate

$$R_{SH} \approx - \frac{dV}{dI} \bigg|_{I = I_{SC}}$$

(E8)

and impose the resulting value on the estimates of the remaining three parameters (i.e., $I_L$, $I_o$ and $R_s$) for an I-V curve, we find that the resulting value for $R_s$ will be orders of magnitude smaller than is credible. From Eq. (10)

$$V = (I_L + I_o - I) R_{SH} - I R_s - nV_{th} W \left( \frac{I_o R_{SH}}{nV_{th}} \exp \left( \frac{I_L + I_o - I}{nV_{th}} \right) \right)$$

$$= (I_L + I_o - I) R_{SH} - I R_s - nV_{th} W (\psi)$$

where

$$\psi = \frac{I_o R_{SH}}{nV_{th}} \exp \left( \frac{(I_L + I_o - I) R_{SH}}{nV_{th}} \right)$$

(E10)

we compute

$$\frac{dV}{dI} = -R_{SH} + R_s \frac{W(\psi)}{\psi \left( 1 + W(\psi) \right)}$$

(E11)
using Eq. (A7). Substituting

$$R_{SH} = -\left. \frac{dV}{dl} \right|_{l=I_{SC}}$$

$$= R_{SH} + R_S - R_{SH} \frac{W(\psi(I_{SC}))}{\psi(I_{SC}) \left(1 + W(\psi(I_{SC}))\right)}$$

leads to

$$R_S = \frac{R_{SH}}{\psi(I_{SC}) \left(1 + W(\psi(I_{SC}))\right)}$$

(E12)

For a reasonable module,

$$\psi(I_{SC}) = \frac{I_o R_{SH}}{nV_{th}} \exp \left(\frac{(I_L + I_O - I) R_{SH}}{nV_{th}}\right)$$

$$\approx 10^{-8} \times 10^3 \exp \left(10^{-1} \times 10^{-1}\right)$$

$$\approx 10^{-5} \exp(50)$$

$$\approx 10^{16}$$

(E14)

which implies that

$$R_S \approx \frac{10^3}{10^{16}}$$

(E15)

which is far too small to be credible.

Figure E2 compares estimates of $R_{SH}$ obtained using the regression method (i.e., [6] with our improvements) to those obtained using the common approximation in Eq. (E8). In this case, the derivative required in Eq. (E8) is computed by averaging the numerical derivatives obtained at each voltage point using [33] for $V < 0.5V_{OC}$. Note that the number of I-V curves with reasonable values for $R_{SH}$ are slightly fewer. The estimates from Eq. (E8) are systematically greater but are likely adequate as initial values for the updating algorithm described in Section 4.2, Step 3. Consequently the advantage of the more complex regression method is to more reliably obtain adequate initial values.
Figure E2. Initial estimates of $R_{SH}$ using different methods.
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